

Update on Cheddar : reviewing Multi-Core and ARINC653 scheduling features, software design exploration

P. Dissaux*, J. Legrand*, A. Schach*, S. Rubini+, J. Boukhobza+,
L. Lemarchand+, J.P. Diguët+, N. Tran+, M. Dridi+,
R. Bouaziz\$, F. Singhoff (speaker)+

* Ellidiss Technologies

+ Lab-STICC UMR CNRS 6285/UBO

\$ ReDCAD Laboratory, University of Sfax



Multiprocessor scheduling analysis with AADLInspector/Cheddar

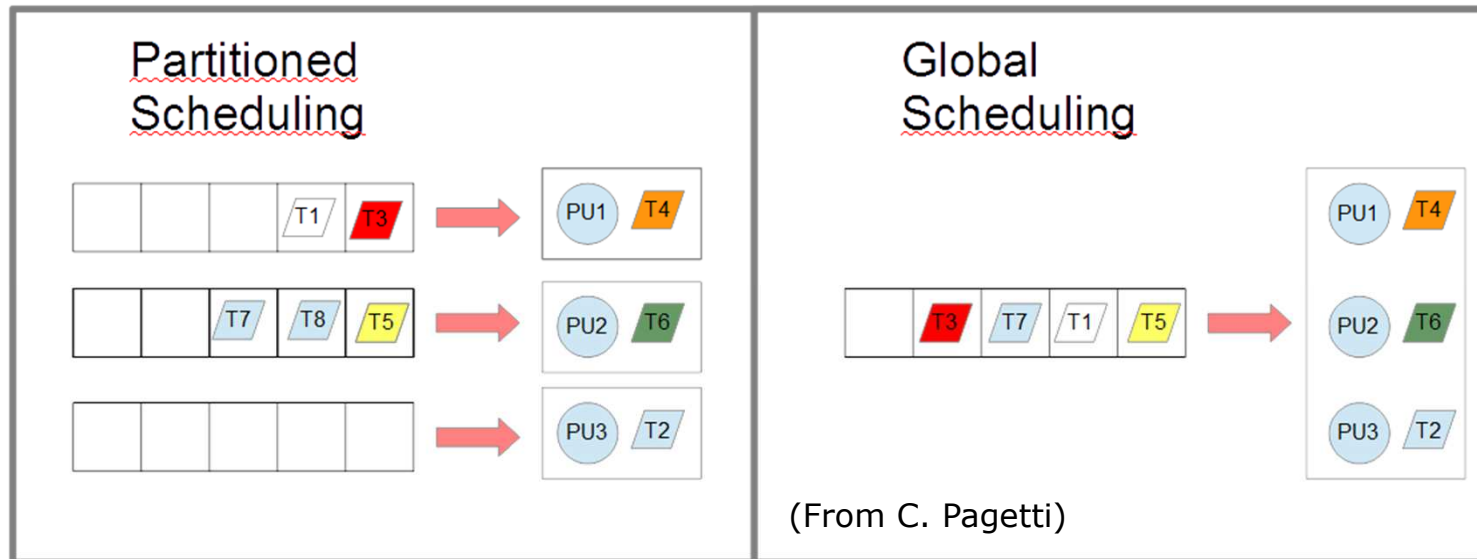
SMART project (completed in 2014):

- Define typical multiprocessor architectures AADLInspector should support (pattern)
- How to model multiprocessor architectures with AADL
- Choose or design new scheduling analysis methods for those patterns
- Prototyping in Cheddar, to be available in AADLInspector

Main outcomes:

1. Implementation of partitioned and global scheduling methods
2. Support of shared resources between processing units
3. Design of partitioning algorithms

Typical multiprocessor scheduling analysis: partitioned vs global



- ❑ **Partitioned scheduling** : first assign off-line each task on a processing unit ; each processing unit schedules its own task set.
 - ❑ No migration. Both on-line and off-line.
- ❑ **Global scheduling**: choose the next task to run on any available processing unit (or preempt if all busy).
 - ❑ With migration. Fully on-line.

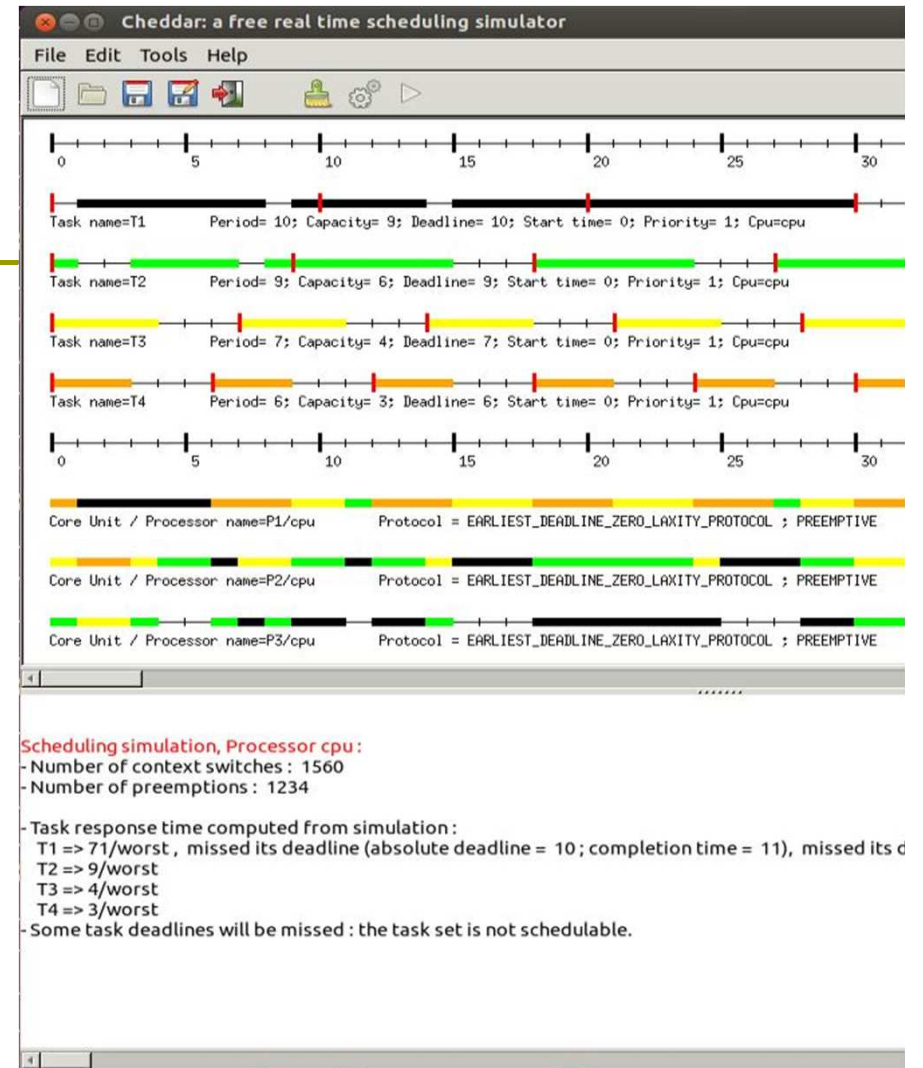
Typical multiprocessor scheduling analysis: partitioned vs global

❑ AADLInspector 1.6 :

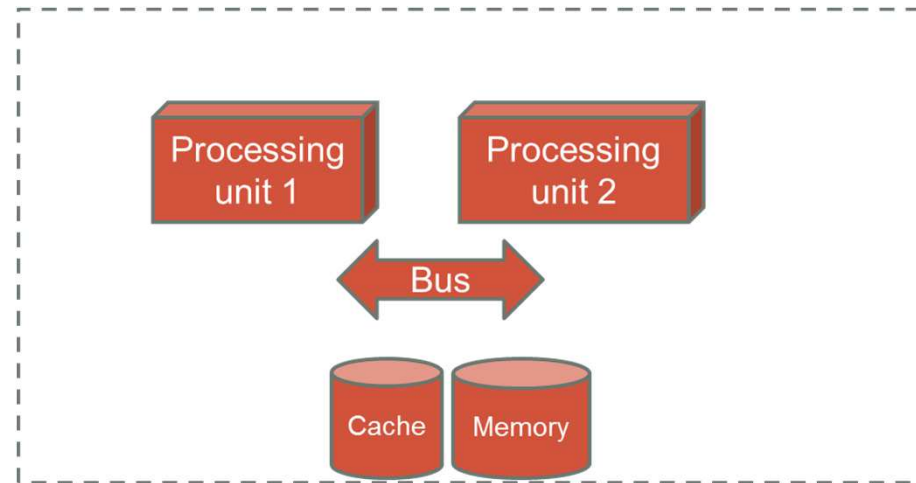
- ❑ Partitioned scheduling only
- ❑ Classical policies (fixed priority, EDF, including ARINC 653, ...)
- ❑ Ravenscar data, data port
- ❑ Scheduling simulation & Response time analysis
- ❑ Partitioning policies: Best fit, First Fit, Next Fit, GT, SF

❑ Cheddar 3.1 only (not in AI yet):

- ❑ Global scheduling : any uniprocessor policies + specific policies such as EDZL, LLREF, Pfair,
- ❑ Partitioning policies based on PAES (Pareto Archived Evolution Strategy)
- ❑ Hardware shared resources support



Shared resources between processing units



- ❑ Shared resources: Cache units, bus, NoC, ...
- ❑ Interferences due to processing units shared resources, make thread WCET (Worst Case Execution Time) difficult to compute
- ❑ Specific scheduling methods

Cache and CRPD

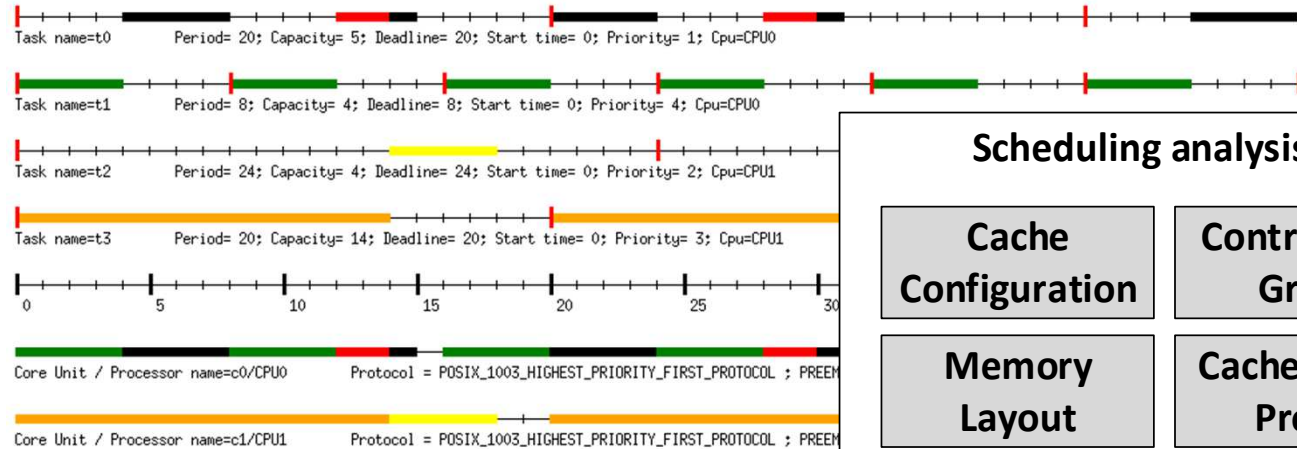
- ❑ In fixed priority preemptive scheduling context, tasks can preempt and evict data of other tasks in the cache.
- ❑ Cache related preemption delay (**CRPD**): additional time to refill the cache with the cache blocks evicted by the preemption.

- ❑ **Some issues:**
 - ❑ CRPD is high, non-negligible preemption cost. It can present up to 44% of the WCET of a task (Pellizzoni et al., 2007)
 - ❑ CRPD is difficult to accurately compute off-line (worst case bound, number of preemption)
 - ❑ Classical scheduling analysis results cannot be applied with CRPD
 - ❑ Applying Rate Monotonic priority assignment algorithm may lead to unschedulable task set
 - ❑ Need new priority assignments taking CRPD into account

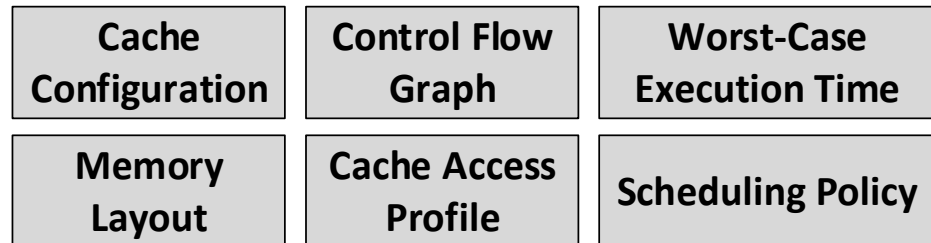
Cache/CRPD-Aware Priority Assignment Algorithms

- ❑ Extend Audsley's priority assignment algorithm (Audsley, 1995) to take into account CRPD.
- ❑ CRPD-aware priority assignment algorithms (**CPA**) that assign priority to tasks and verify their schedulability.
- ❑ 4 algorithms with different levels of schedulability efficiency and complexity.
- ❑ Implemented into Cheddar 3.1, not available with AADLInspector 1.6

Cache-Aware Scheduling Simulation



Scheduling analysis for systems with cache



❑ Problem Statement:

- ❑ Theoretical issues with CRPD : feasibility interval, sustainability
- ❑ Various parameters need to be taken into account in scheduling analysis of systems with cache: cache profile, memory layout, CFG

❑ Outcomes:

- ❑ We have designed a new CRPD computation model, sustainable for L1 instruction cache. Feasibility interval proved.
- ❑ Extending Cheddar to model cache/cache access profile

Summary

- 1. Multiprocessor scheduling analysis features**
- 2. Software design space exploration : partitioning with competing objective functions**

Cheddar & partitioning with competing objective functions

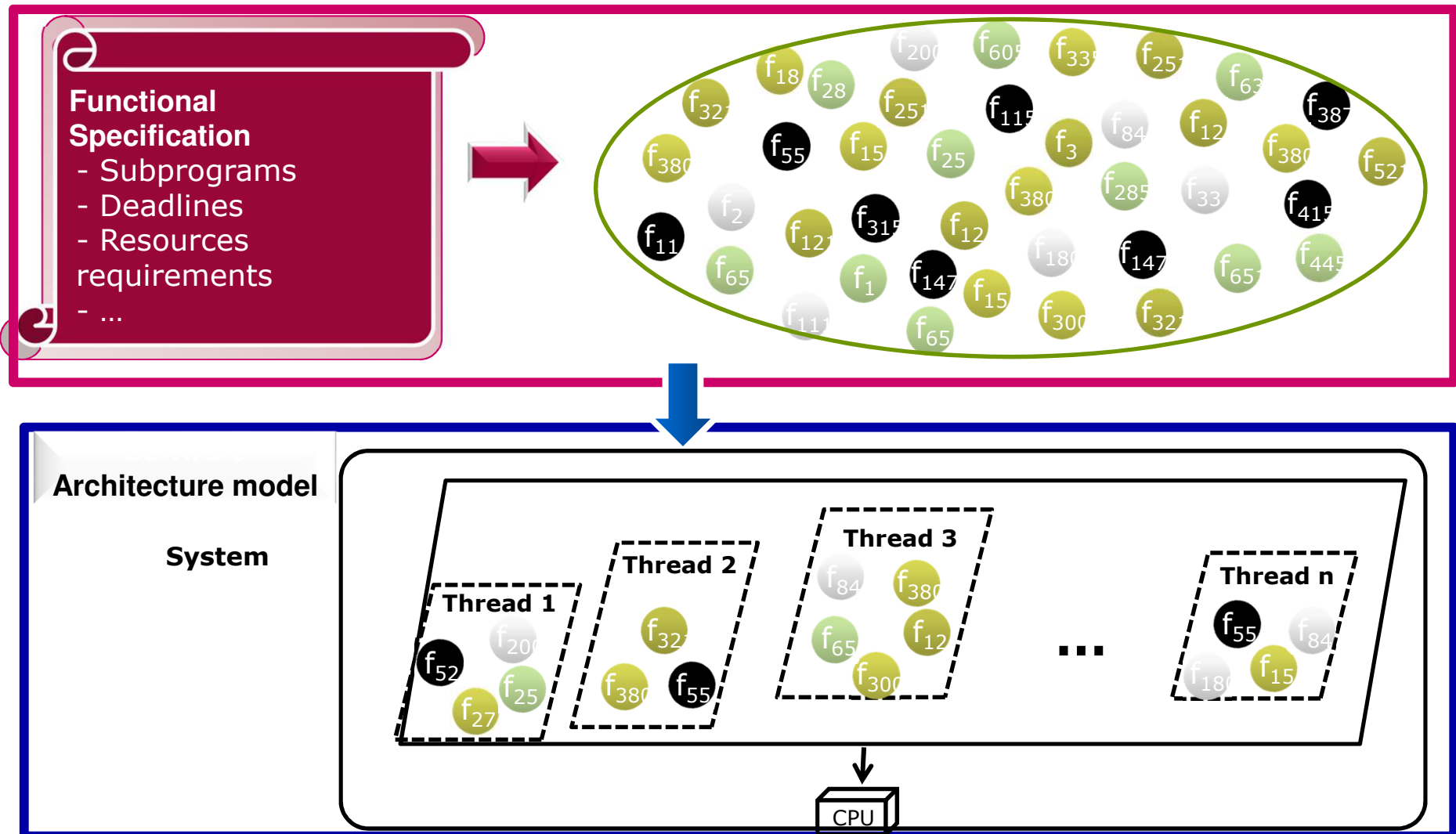
Problem statement :

- Performances (scheduling), is not the unique concern
- Trade-offs with several competing criteria/objective functions such as performances vs safety vs security
- How to do partitioning in this context ?
- PAES helps ? PAES with Cheddar ?

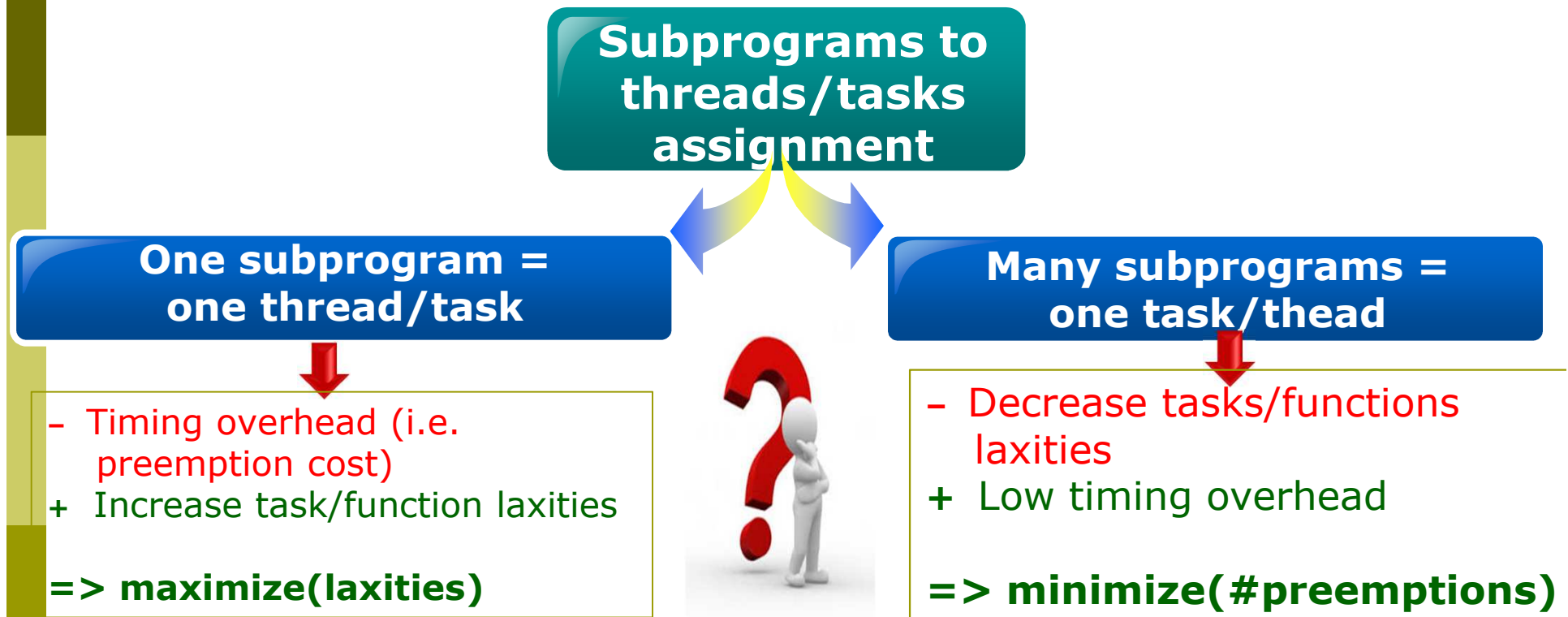
Small example to illustrate, assume:

- A system running several sub-programs (i.e. functional units)
- Subprograms may shared resources (compliant with Ravenscar)
- How to assign subprograms to threads

From the functional specification to a software architecture



Competing objective functions in software design space exploration



Explore several assignment solutions

Select assignment solutions that meet at **best the trade-offs between number of preemptions and laxities**

PAES : a multi-objectives metaheuristic

□ Basic steps of PAES algorithms:

1

Mutate a solution to generate a new candidate: small change to move from a solution to a nearby neighbour

2

Evaluate the mutated solution (conflicting objective functions)

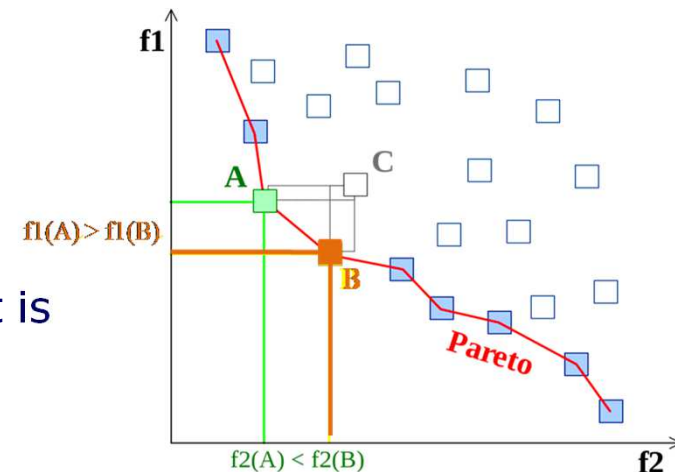
3

Update non-dominated solutions set (i.e. archive)

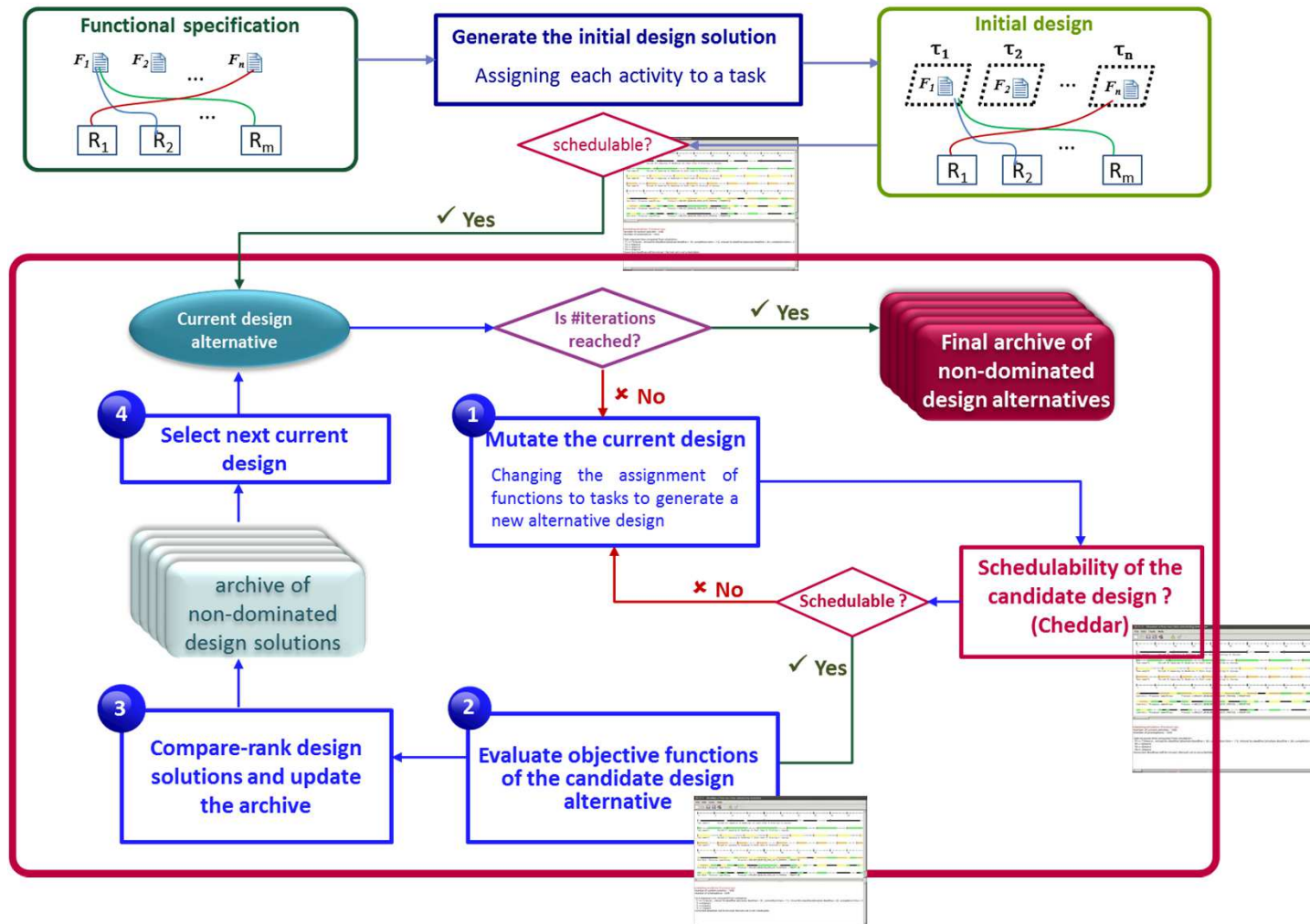
4

Select new solution for next iteration : mutated or current solution

- **Pareto Front**: final set of non-dominated solutions
 - Solutions A dominates solution C because it is better than C for all objectives



PAES-based partitioning



Competing Performance Criteria in the Software Design Space exploration

□ Examples of investigated trade-offs with competing objectives functions such as:

- Min (#preemptions)

- Max (laxities)

- Min (Ravenscar data blocking time)

- ...

⇒ Performance competing objectives functions only

□ How to be sure that objective functions are competing?

Conclusion

- ❑ **Multiprocessor scheduling analysis of AADLInspector & Cheddar:**
 - ❑ Bunch of classical partitioned vs global scheduling algorithms
 - ❑ Shared hardware resources: cache, NoC

- ❑ **Multi-objective partitioning**
 - ❑ PAES based, for Ravenscar compliant architecture
 - ❑ Safety & performance & security objective functions
 - ❑ Follow Security annex