



Validation de systèmes temps-réel et embarqué à partir d'un modèle MARTE

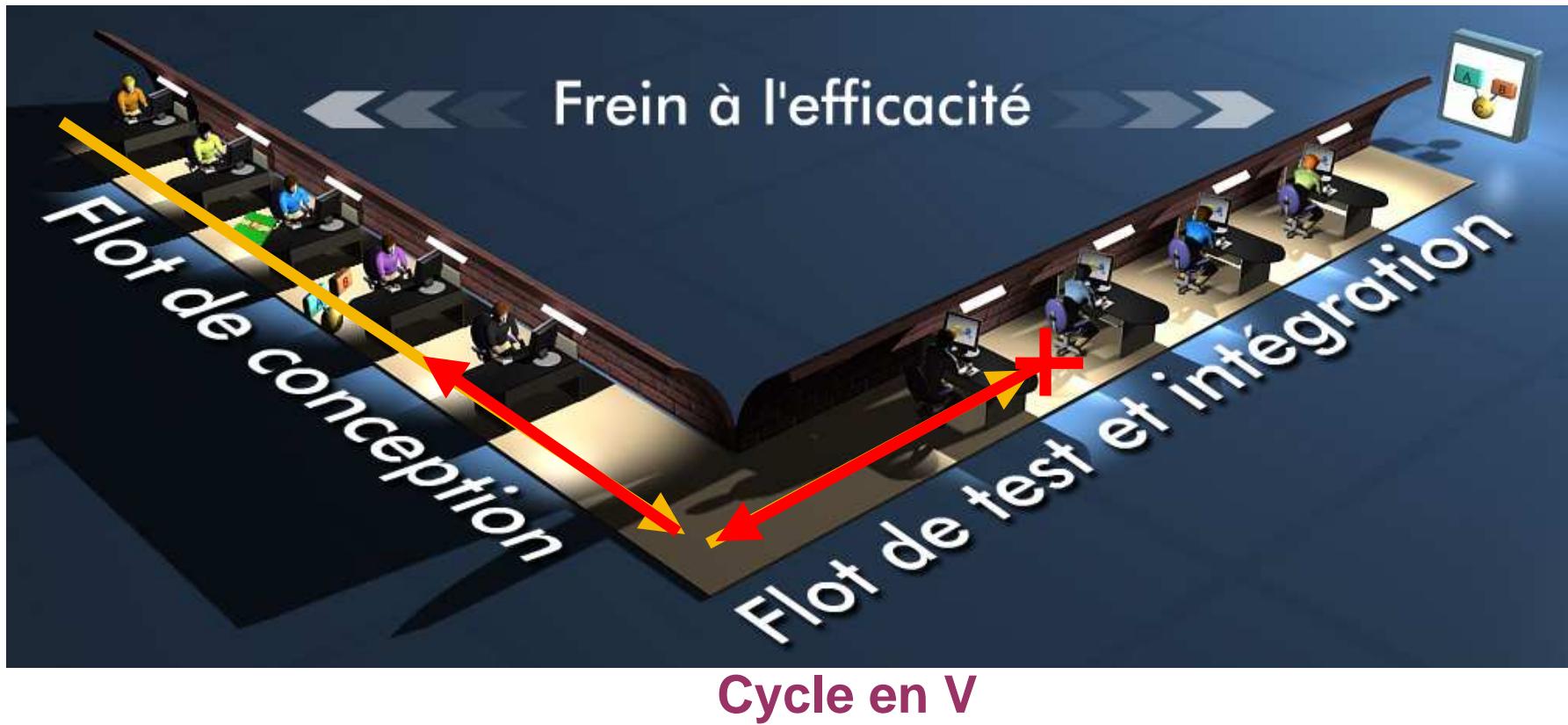
Thales Research and Technology

Eric MAES (eric.maes@thalesgroup.com)

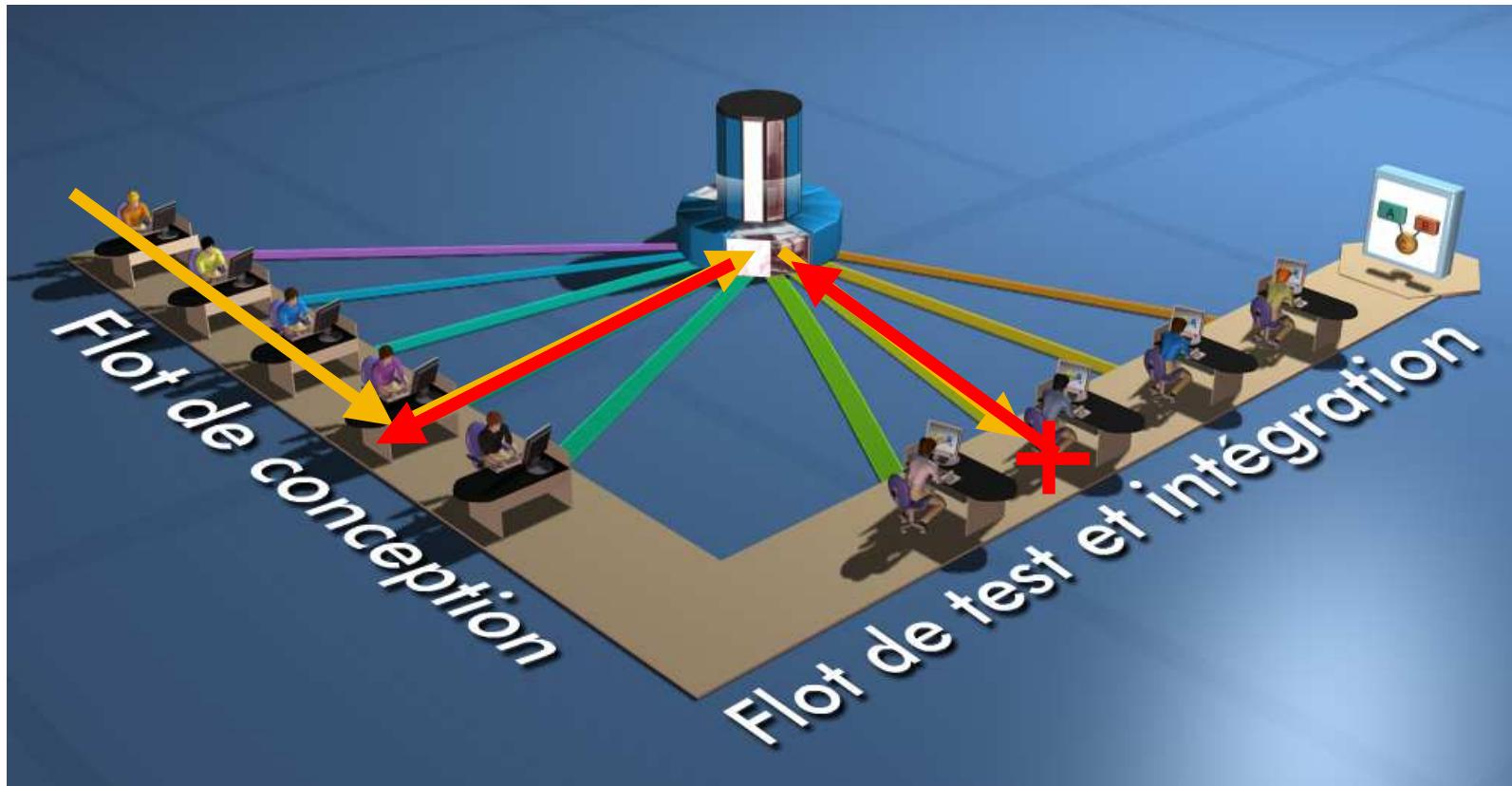


- I - Besoins dans le processus de développement**
- II - MARTE : profil UML standard pour le temps-réel et l'embarqué**
- III – Expérimentation**
 - III.a - Chaîne outillée de l'expérimentation**
 - III.b - Cas d'étude de l'expérimentation**
 - III.c - Modélisation du cas d'étude**
 - III.d - Règles de transformation**
 - III.e - Analyse d'ordonnançabilité pour le cas d'étude**
- VIII - Conclusion**

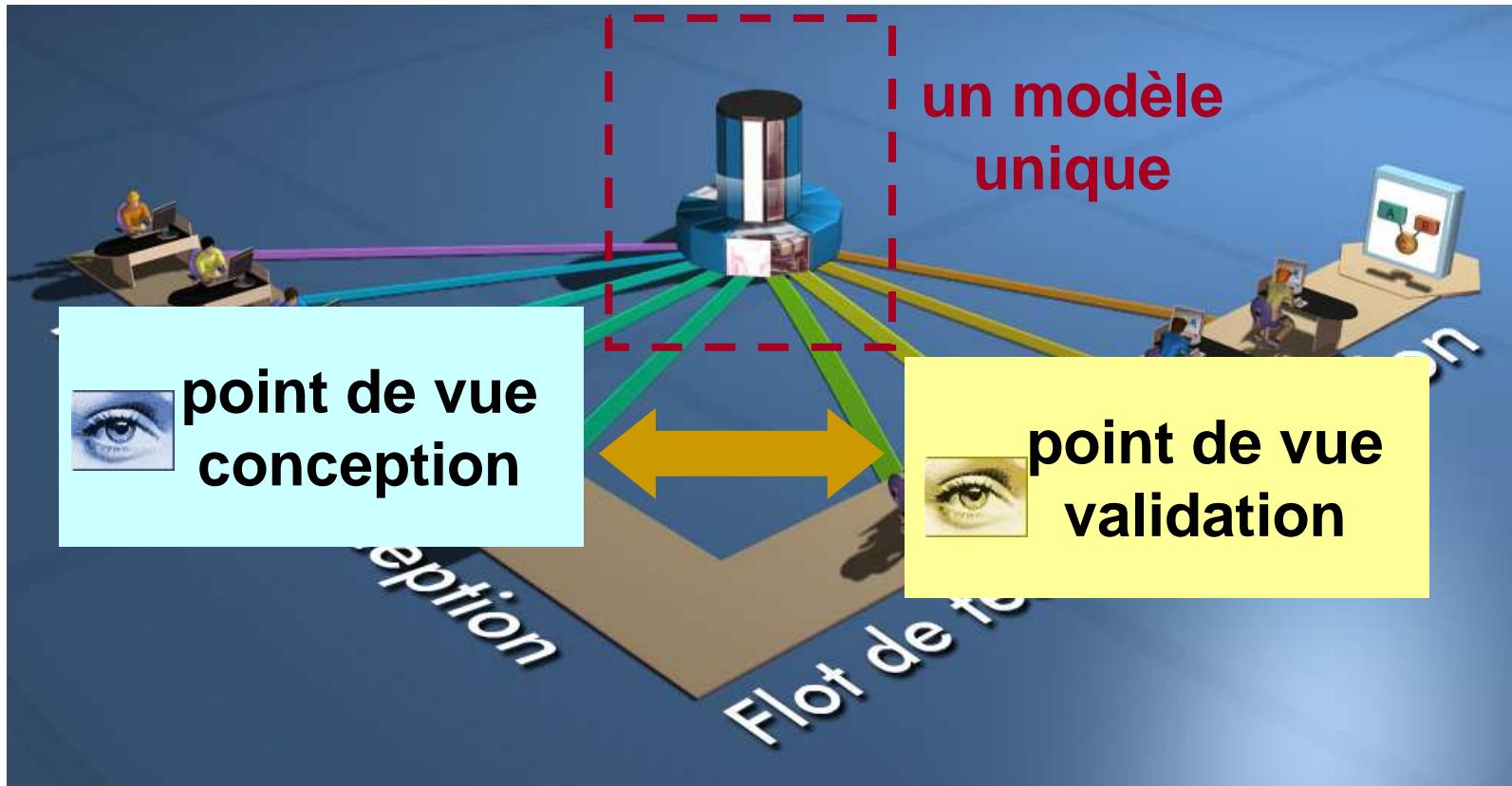
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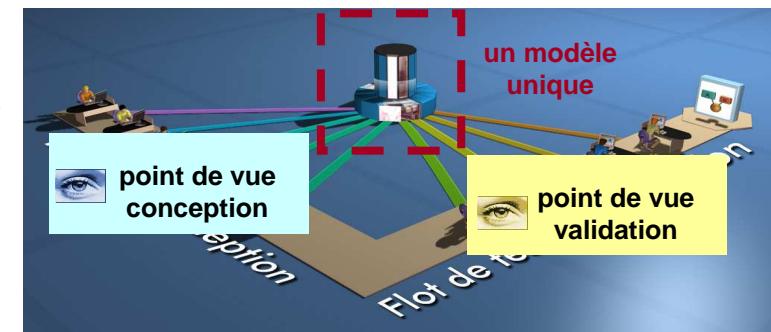
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Ingénierie dirigée par les modèles

- UML



Insuffisant



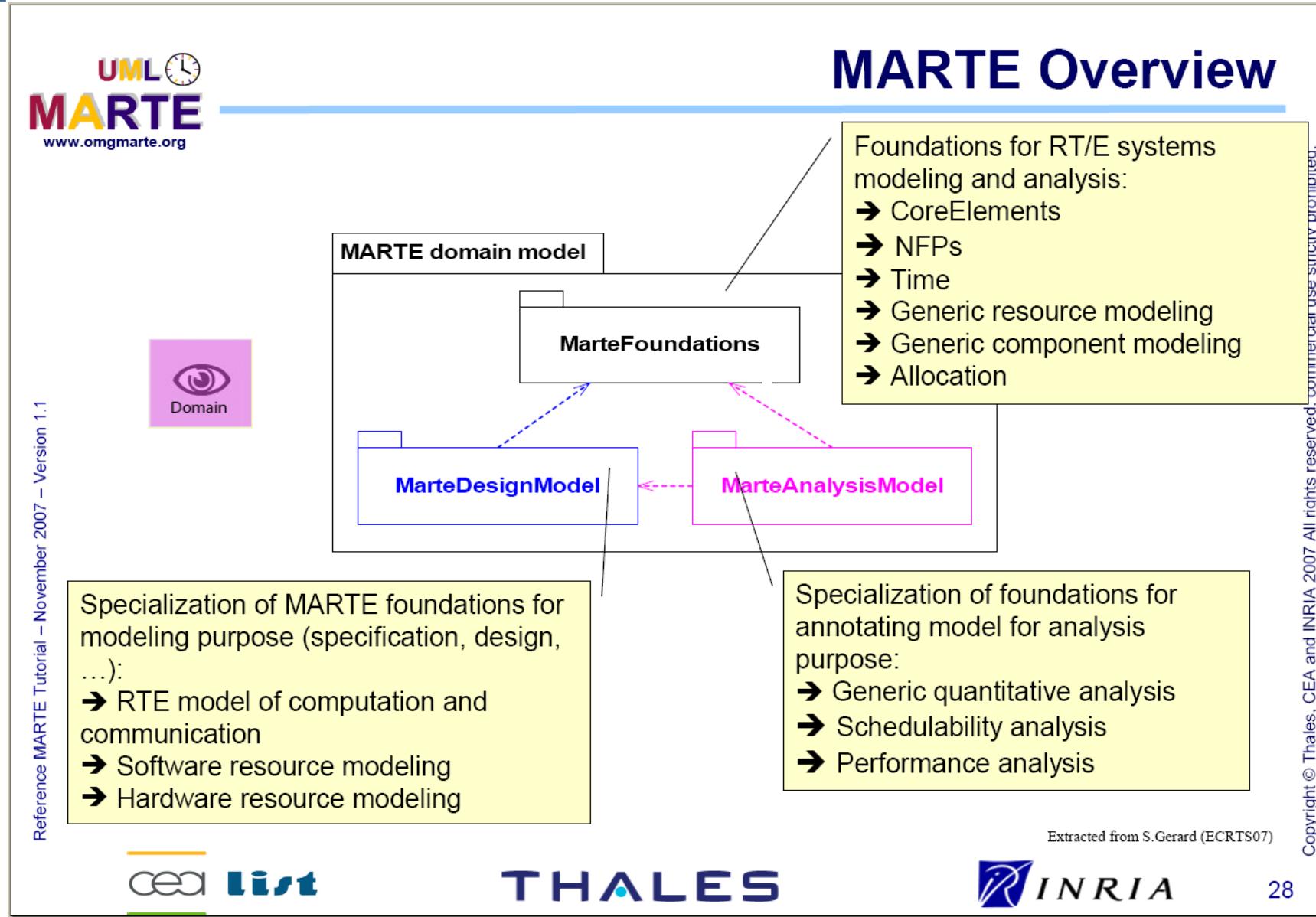
- MARTE

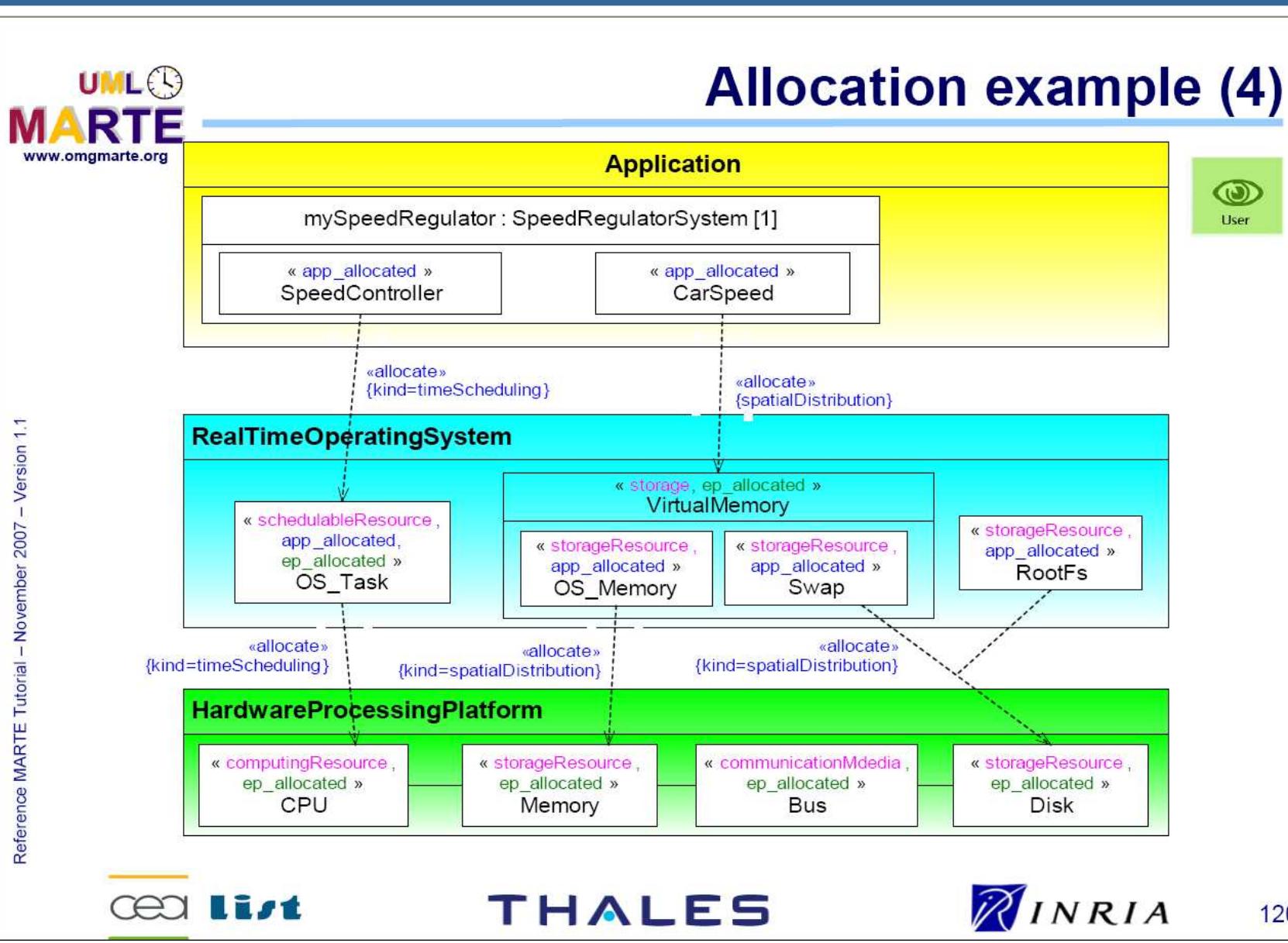


Modeling and Analysis for Real-Time and Embedded systems

Standard OMG : Profil UML pour le développement de systèmes temps-réel et embarqué

www.omgmarте.org



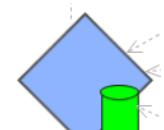




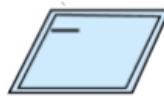
ComputingResource : either virtual or physical processing device capable of storing and executing program code



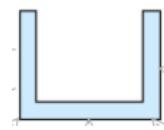
Scheduler : kind of ResourceBroker that brings access to its broked ProcessingResource or resources following a certain scheduling policy



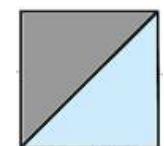
StorageResource : different forms of memory



SwSchedulableResource : resources which executes concurrently to other concurrent resources



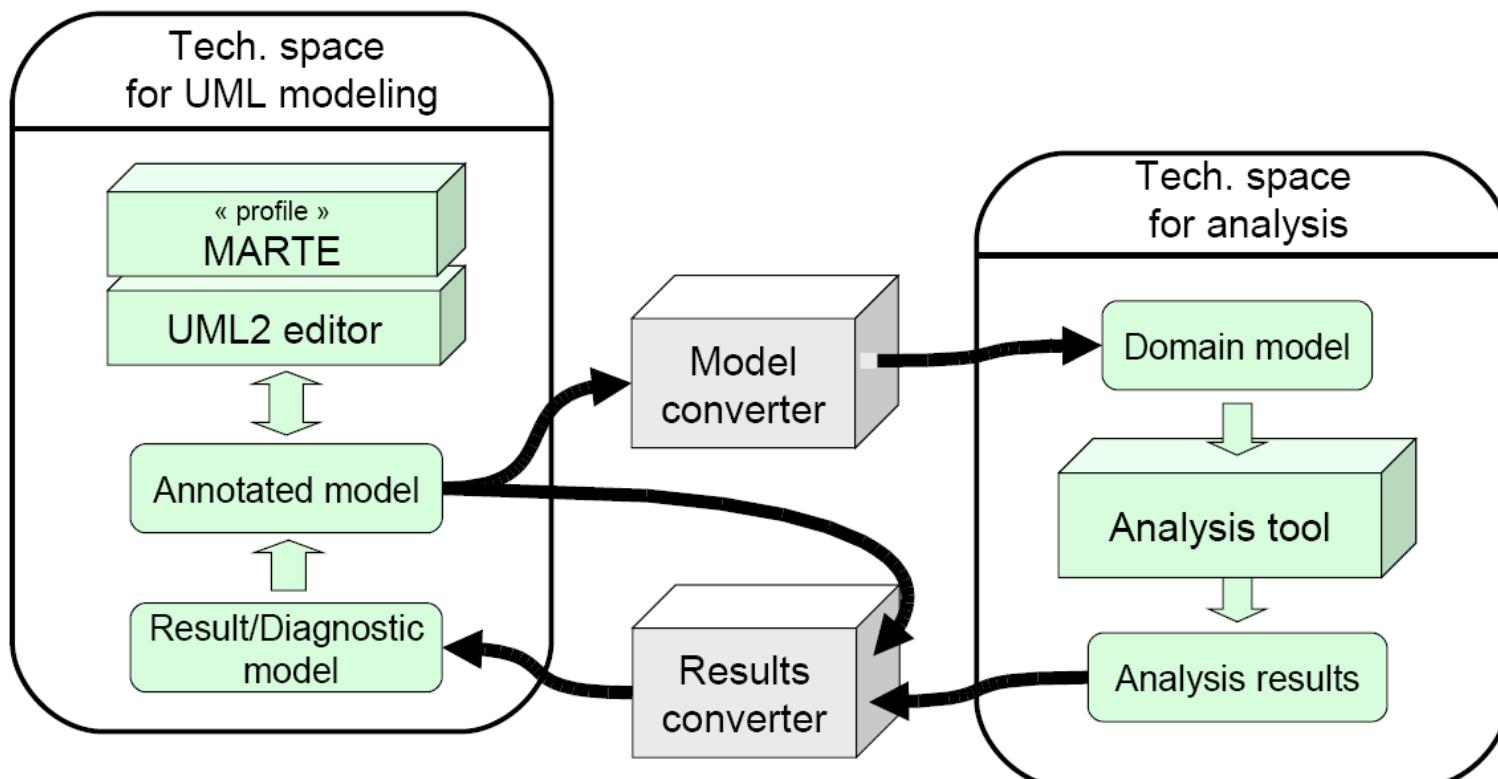
MemoryPartition : virtual address space



SwMutualExclusionResource : resources commonly used for synchronize access to shared variables



Processing Schema for Analysis

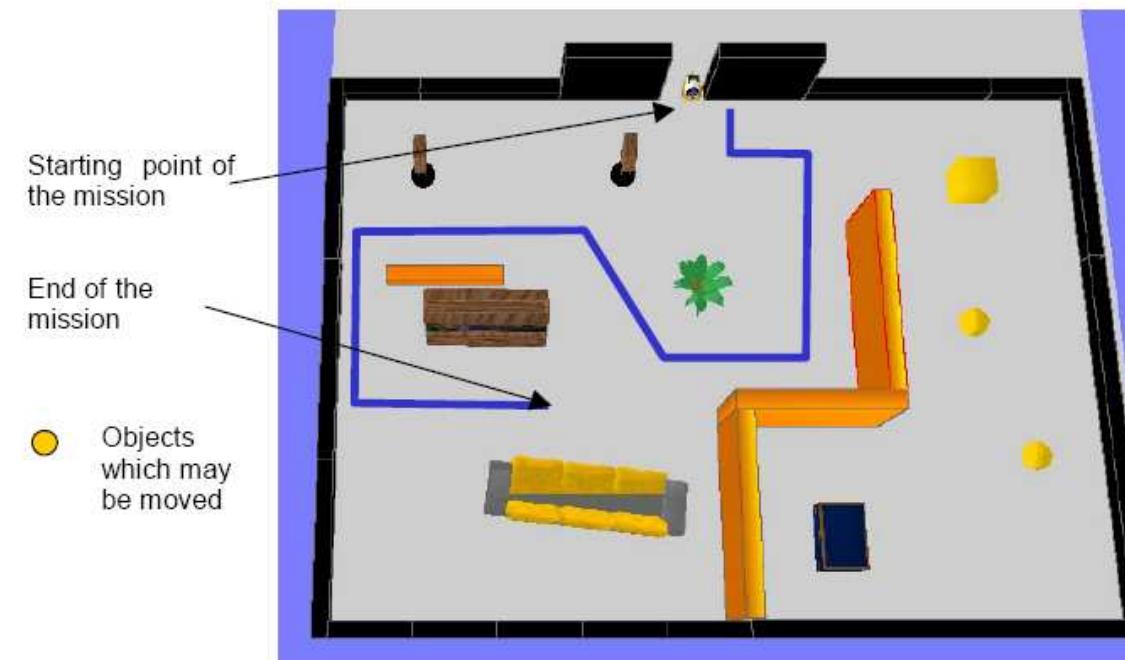






- Robot

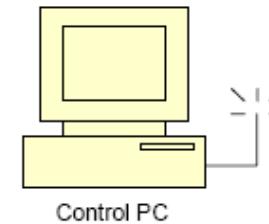
- ▶ Mission : relever la température le long d'un chemin
- ▶ Autonome
- ▶ Contraintes temps réel
 - ▶ Envoi de la position toutes les 50 ms
 - ▶ Envoi de la température toutes les 250 ms



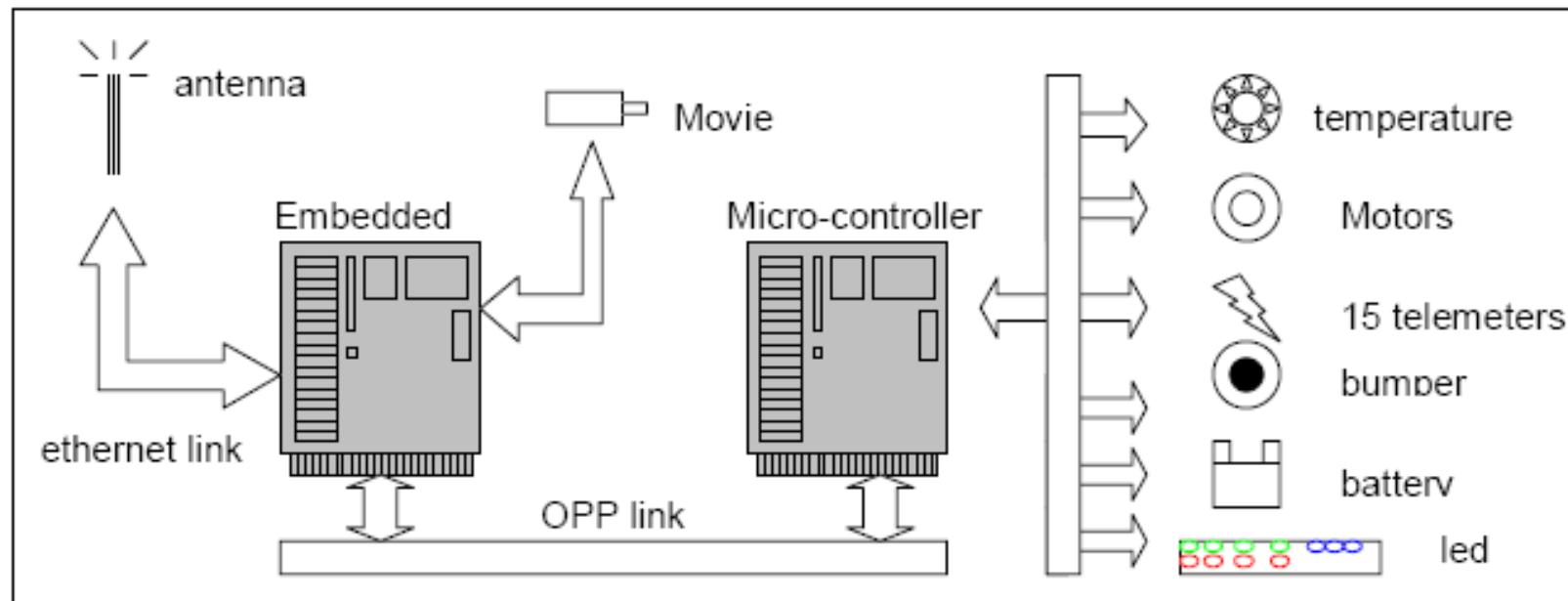
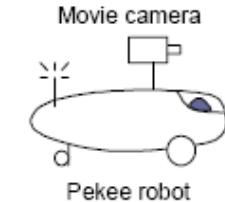


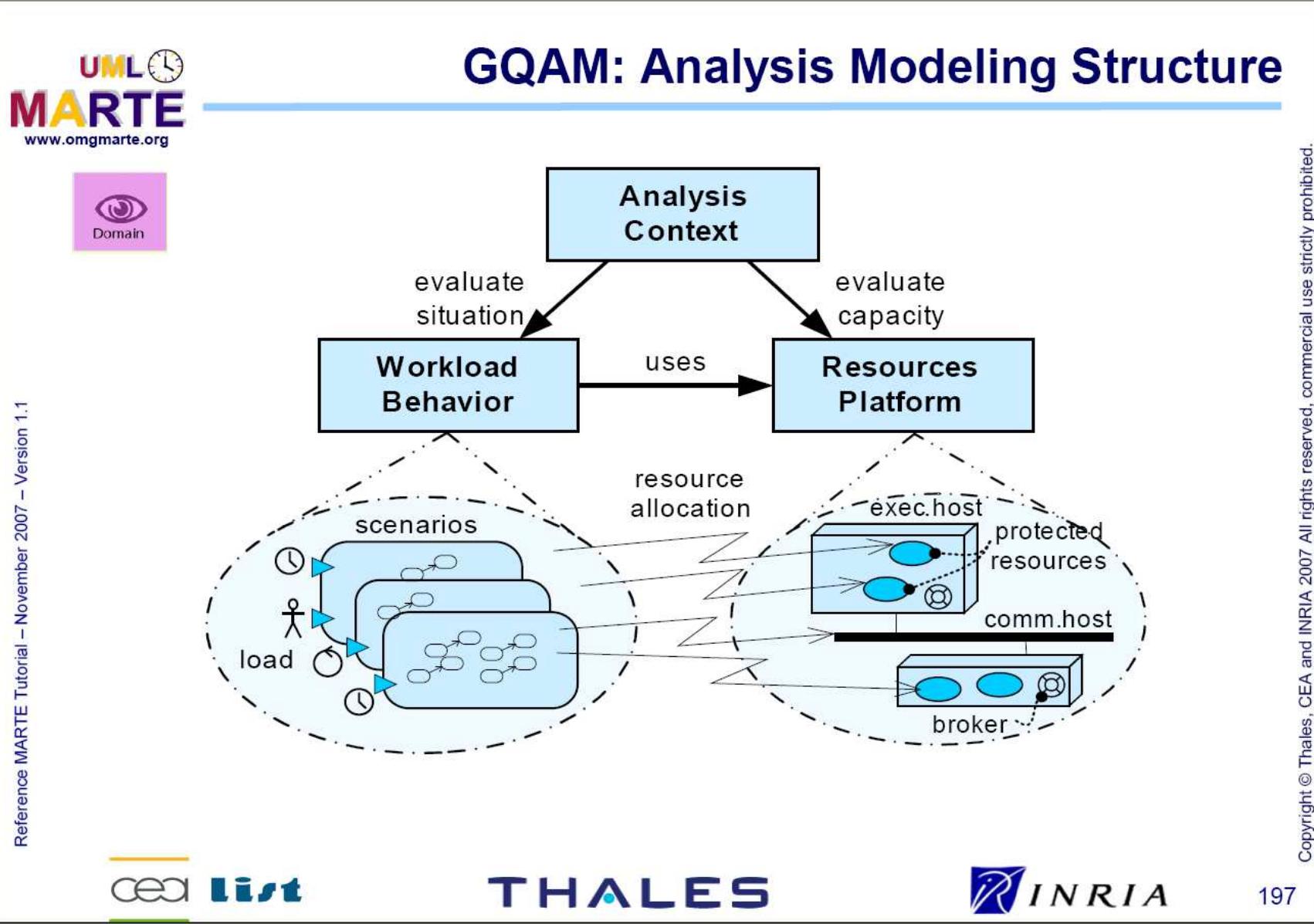
- **Architecture**

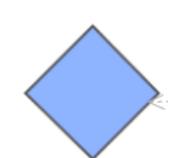
- ▶ PC de contrôle
- ▶ Microcontrôleur
- ▶ **PC embarqué**



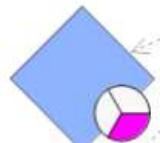
Ethernet wireless link



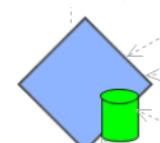




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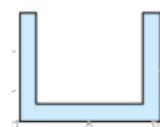
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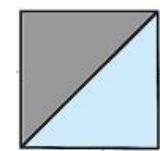
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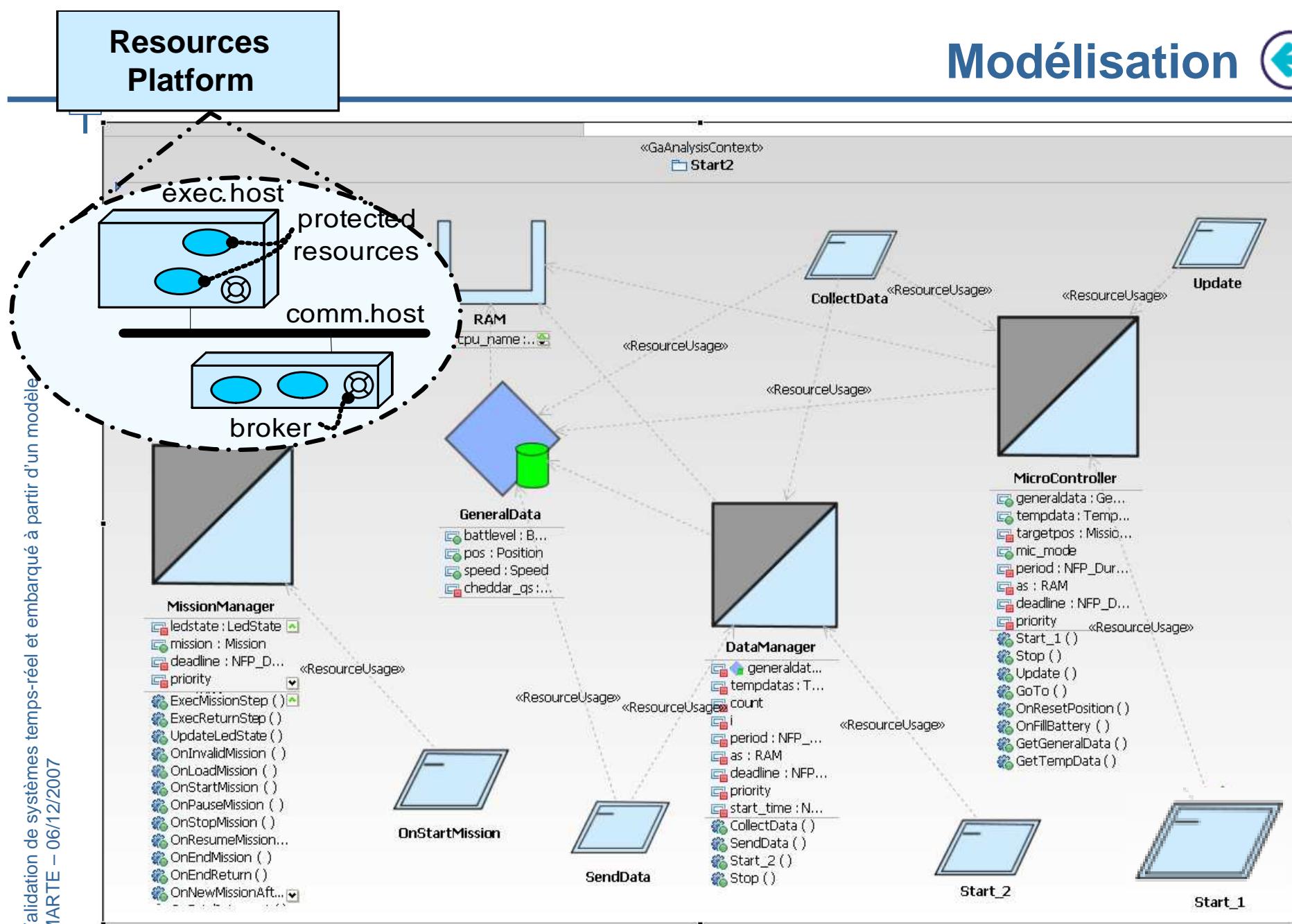


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Modélisation

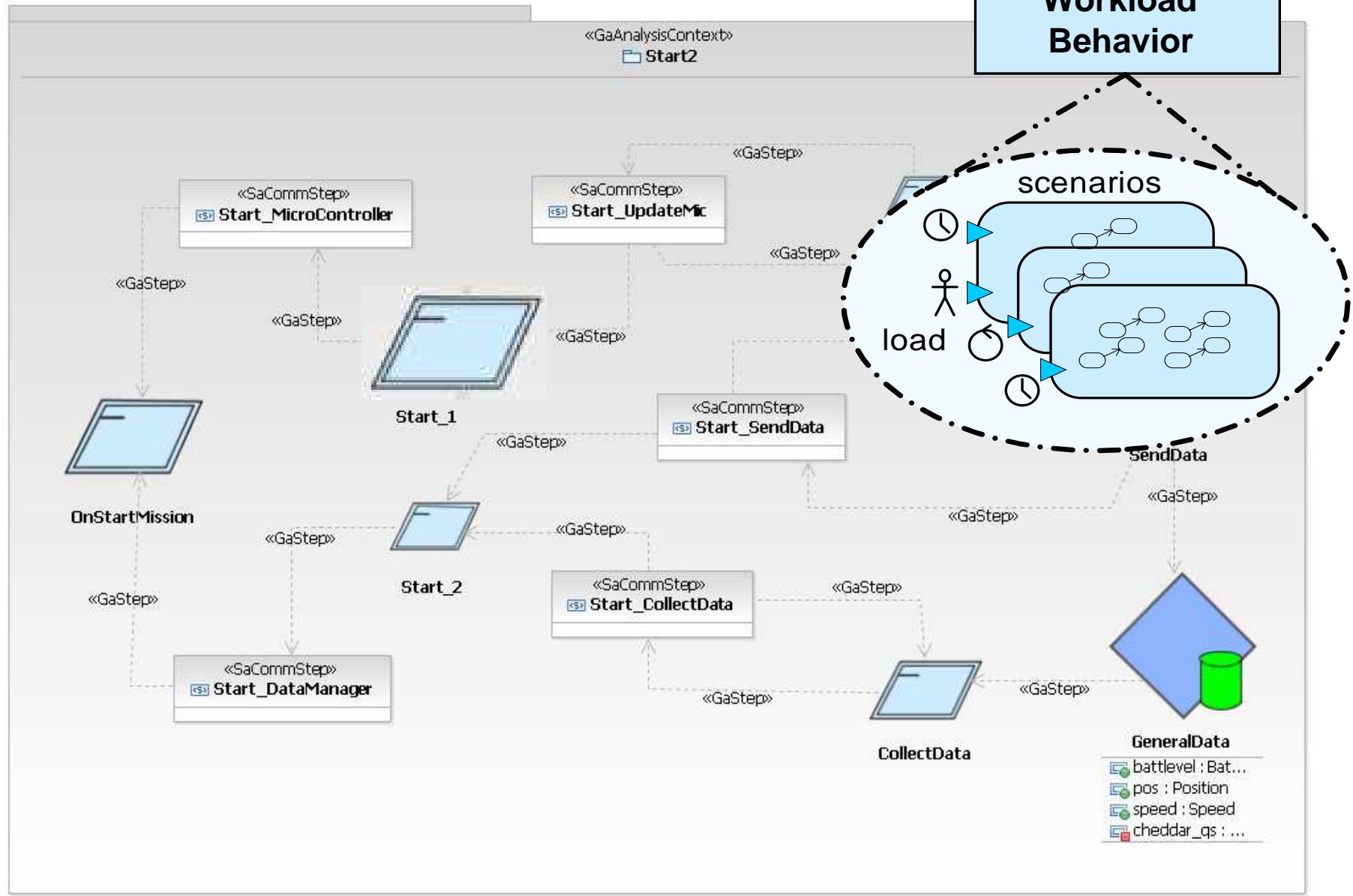


Modélisation

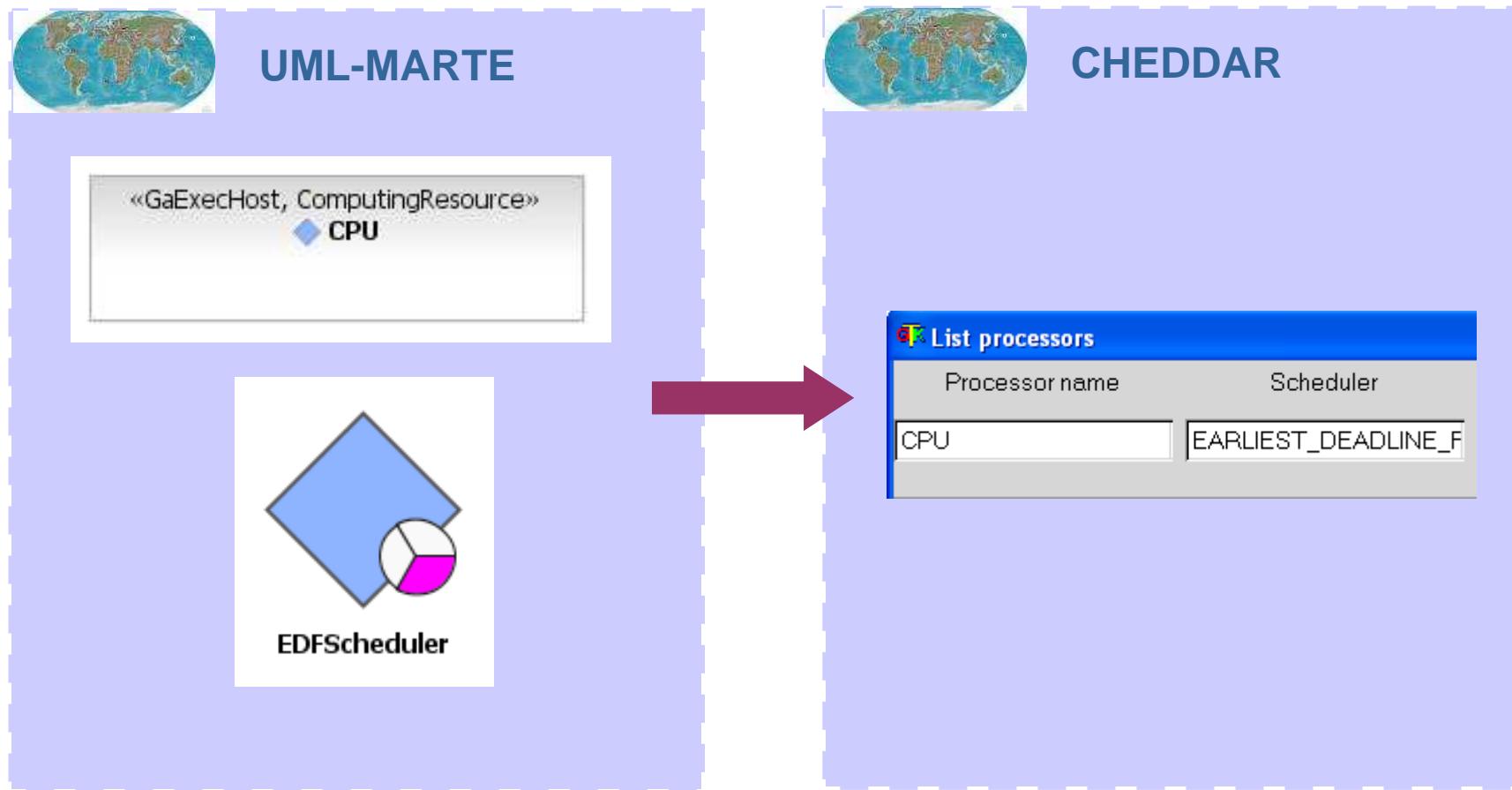


Workload Behavior

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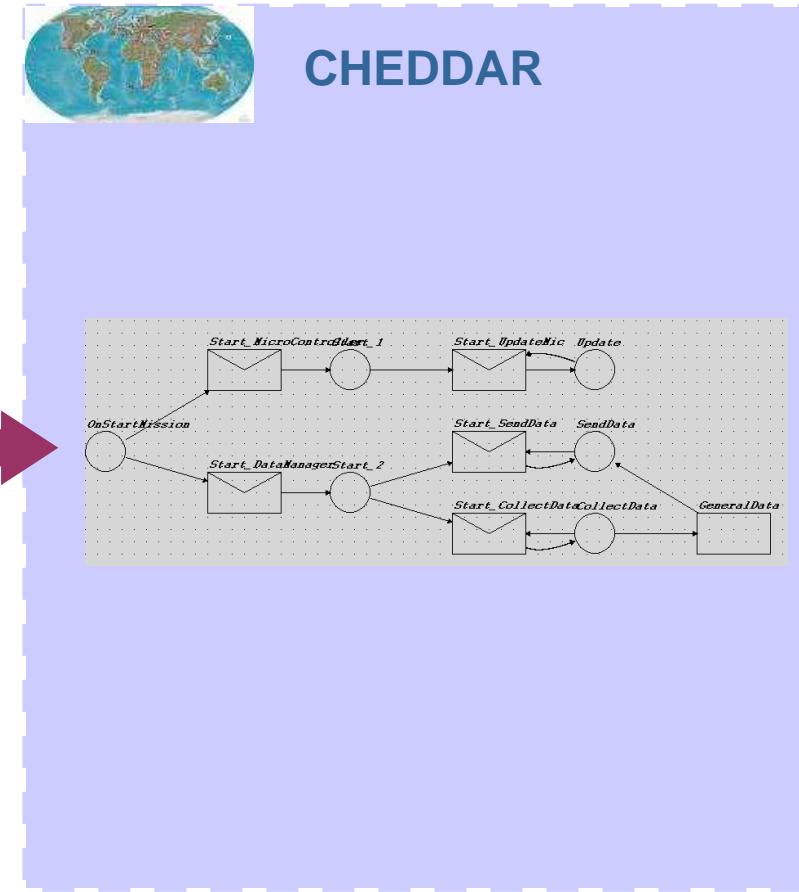
Règles de transformation entre concepts des deux mondes





Règles de transformation entre concepts des deux mondes

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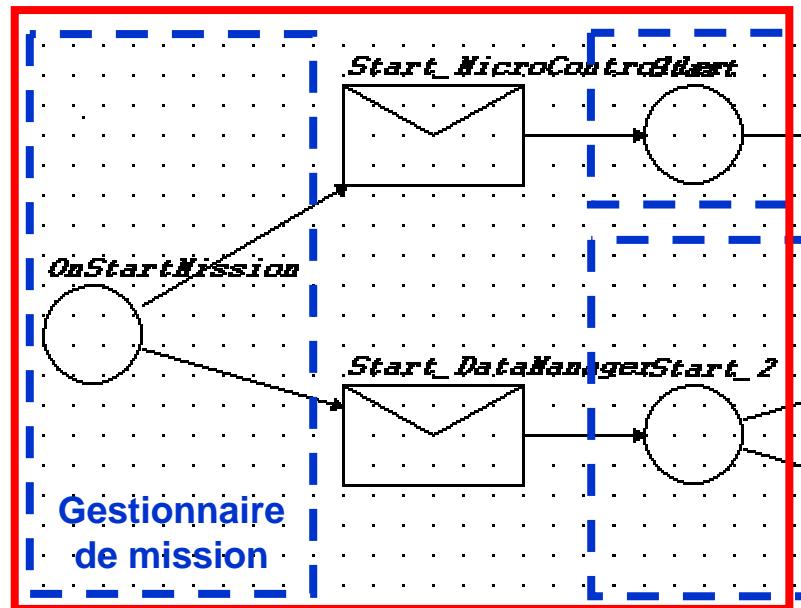




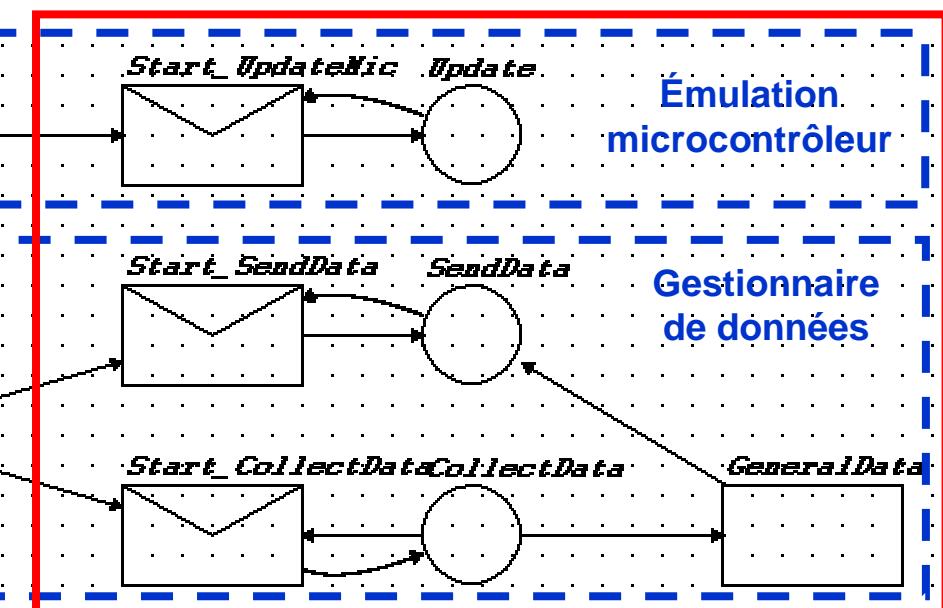
- Scénario : Démarrage du robot

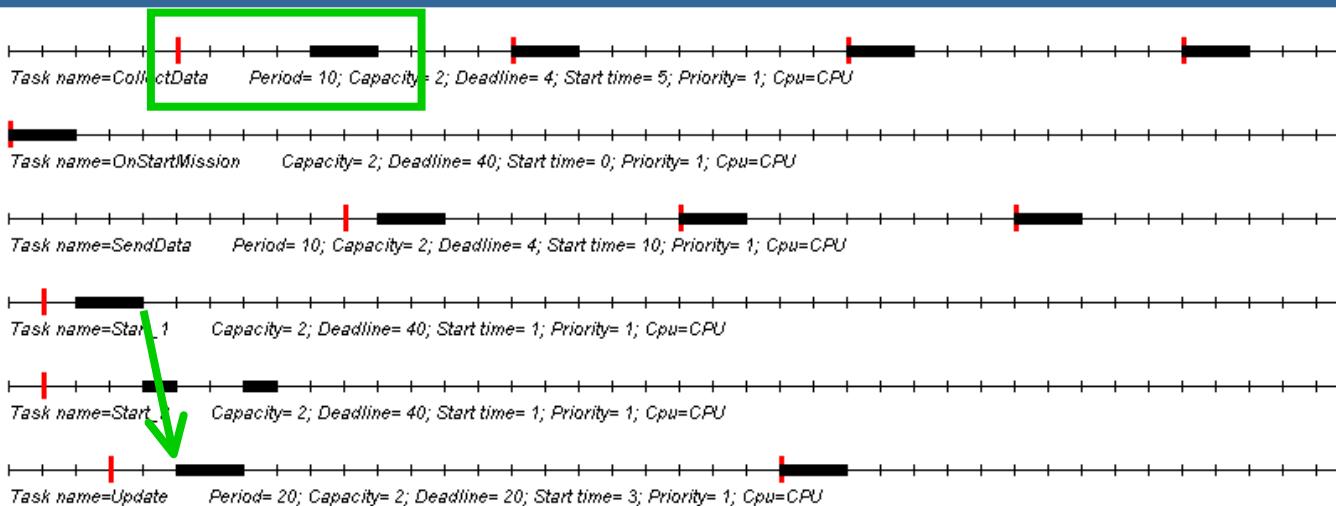
- ▶ Cascade de tâches qui déclenchent les tâches périodiques
- ▶ Retard des messages

Démarrage



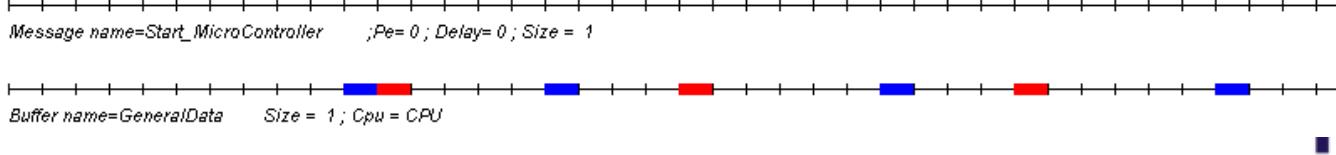
Fonctionnement général





Scheduling simulation, Processor CPU :

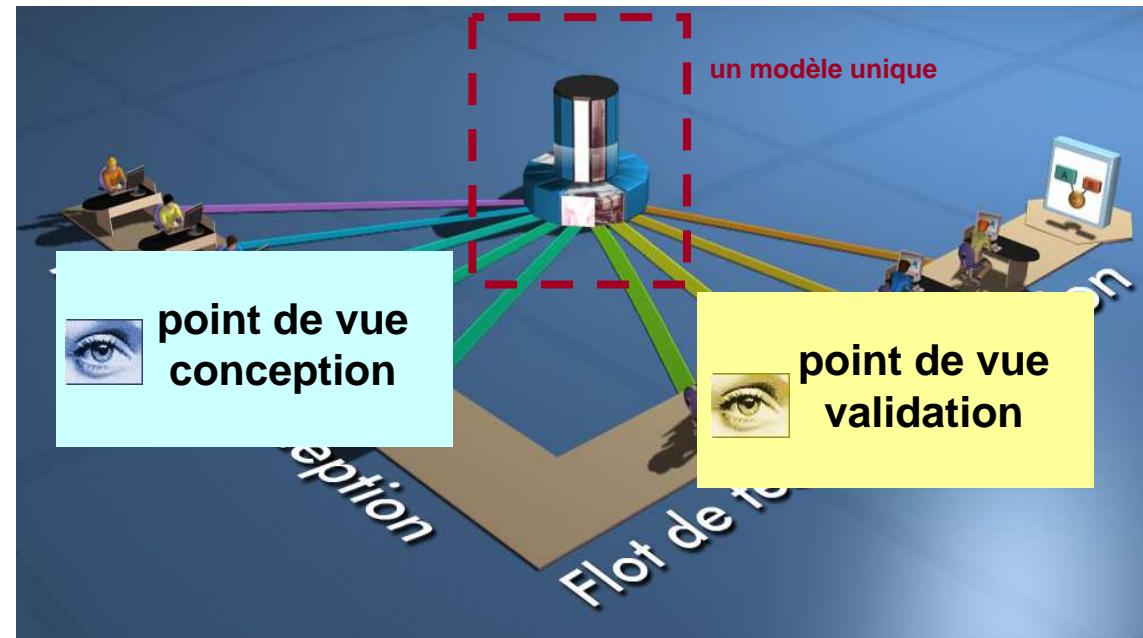
- Number of context switches : 12
- Number of preemptions : 1
- Task response time computed from simulation :
 - CollectData => 5/worst , missed its deadline (deadline = 9 ; completion time = 11)
 - OnStartMission => 2/worst
 - SendData => 3/worst
 - Start_1 => 3/worst
 - Start_2 => 7/worst
 - Update => 4/worst
- Some task deadlines will be missed : the task set is not schedulable.



- Chaîne outillée centrée sur un modèle unique

- Conception
- Validation intégralement automatisée

⇒ possibilités de correction en amont





- MARTE to Cheddar



Eric MAES (eric.maes@thalesgroup.com)

Nicolas VIENNE

- MARTE

- website : <http://www.omgarte.org>
- tutorial : <http://www.omgarte.org/Tutorial.htm>
- MARTE for RSA : <http://www.omgarte.org/Tools.htm>



- Cheddar

- <http://beru.univ-brest.fr/~singhoff/cheddar/index-fr.html>

- Josefil

- <http://www.cs.unibo.it/~cianca/wwwpages/sfida.pdf>



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